Positive operators, Z-operators, Lyapunov rank, and linear games on closed convex cones

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PART 1, SECTION 1

Introduction: Definitions

Everything takes place in a Hilbert space V:

- V is finite-dimensional.
- V is a vector space over the real numbers.

Definition (cones).

A *cone* is a set K such that $\lambda K \subseteq K$ for all $\lambda > 0$.

A closed convex cone is a cone that is closed and convex as a set.

A *proper* cone is a closed convex cone that has interior and contains no lines.

Definition (dual cone).

The dual cone K^* of a set K is

$$K^* := \{ y \in V \mid \langle y, x \rangle \ge 0 \text{ for all } x \in K \},$$

The dual cone is always a closed convex cone.

If K is a proper cone, then K^* is too.

Definition (positive operator).

The linear operator L is *positive* on K if

$$L(K) \subseteq K$$
.

The set of all positive operators on K is $\pi(K)$.

Example. Nonnegative matrices are $\pi(\mathbb{R}^n_+)$.

Definition (complementarity set).

The *complementarity set* of a cone K is,

$$C\left(K\right) \coloneqq \left\{\left(x,s\right) \in K \times K^* \mid \langle x,s \rangle = 0\right\}.$$

Definition (Z-operator).

The linear operator L is a \mathbf{Z} -operator on K if

$$\langle L(x), s \rangle \leq 0$$
 for all $(x, s) \in C(K)$.

The set of all **Z**-operators on K is $\mathbf{Z}(K)$.

Definition (Lyapunov-like operator).

The linear operator L is Lyapunov-like on K if

$$\langle L(x), s \rangle = 0 \text{ for all } (x, s) \in C(K),$$

The set of all Lyapunov-like operators on K is

$$\mathbf{LL}\left(K\right) = -\mathbf{Z}\left(K\right) \cap \mathbf{Z}\left(K\right).$$

Definition (Lyapunov rank).

The $Lyapunov \ rank \ of \ K$ is

$$\beta\left(K\right) = \dim\left(\mathbf{LL}\left(K\right)\right).$$

Motivation.

A cone complementarity problem is to

find
$$(x, f(x)) \in C(K)$$
.

This condition gives us $\beta(K)$ equations.

Part 2, Section 2

Results: Positive & Z-operators

Theorem (Tam, 1977).

If K is a proper cone, then

$$\pi(K)^* = \operatorname{cone}(\operatorname{Ext}(K^*) \otimes \operatorname{Ext}(K)).$$

Theorem (Orlitzky, 201X).

If
$$K = \operatorname{cone}(G_1)$$
 and if $K^* = \operatorname{cone}(G_2)$, then
$$\pi(K)^* = \operatorname{cone}(\{s \otimes x \mid (x, s) \in G_1 \times G_2\}).$$

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RESULTS: POSITIVE & Z-OPERATORS

The algorithm is available in SageMath:

```
sage: K = Cone([ (1,0), (0,1) ])
sage: K.positive_operators_gens()
[
[1 0] [0 1] [0 0] [0 0]
[0 0], [0 0], [1 0], [0 1]
]
```

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RESULTS: POSITIVE & Z-OPERATORS

Theorem (Schneider & Vidyasagar, 1970).

If K is a proper cone, then $\pi(K)$ is too.

Theorem (Orlitzky, 201X).

If K is a closed convex cone, then K is proper if and only if $\pi(K)$ is proper.

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Theorem (Tam, 1977).

If K is a proper cone, then K is polyhedral if and only if $\pi(K)$ is polyhedral.

Theorem (Orlitzky, 201X).

If K is a closed convex cone, then K is polyhedral if and only if $\pi(K)$ is polyhedral.

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Theorem (Orlitzky, 201X).

If $K = \text{cone}(G_1)$ and if $K^* = \text{cone}(G_2)$, then $\mathbf{Z}(K)^*$ is the *conic* hull of

$$\{-s \otimes x \mid (x,s) \in G_1 \times G_2 \text{ and } \langle x,s \rangle = 0\}.$$

This suggests an algorithm to find $\mathbf{Z}(K)$.

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The algorithm is available in SageMath:

```
sage: K = Cone([ (1,0), (0,1) ])
sage: K.Z operators gens()
[0 -1] [0 0] [-1 0]
[0 0], [-1 0], [0 0],
[1 \ 0] \ [0 \ 0] \ [0 \ 0]
[0 0], [0 -1], [0 1]
```

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RESULTS: POSITIVE & Z-OPERATORS

Theorem (Orlitzky, 201X).

If K is a closed convex cone, then K is polyhedral if and only if $\mathbf{Z}(K)$ is polyhedral.

Corollary.

If K is a closed convex cone, then $\pi(K)$ is polyhedral if and only if $\mathbf{Z}(K)$ is polyhedral.

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Theorem (Orlitzky, 201X).

If K is a closed convex cone, then

$$\dim (\pi (K)) = \dim (\mathbf{Z} (K)).$$

"Obvious" for proper K, but not in general.

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Theorem (Schneider & Vidyasagar, 1970).

If K is proper in \mathbb{R}^n and if $A \in \mathbb{R}^{n \times n}$, then

$$A \in \mathbf{Z}(K) \iff e^{-tA} \in \pi(K) \text{ for all } t \ge 0.$$

Theorem (Orlitzky, 201X).

If K is a closed convex cone and L is linear, then

$$L \in \mathbf{Z}(K) \iff e^{-tL} \in \pi(K) \text{ for all } t \geq 0.$$

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Part 2, Section 3

Results: Improper cone rank

Lemma (Rudolf et al., 2011).

If K is a proper cone, then

L is Lyapunov-like on K

$$\iff$$

 $\langle L(x), s \rangle = 0$ for all $x \in \text{Ext}(K)$ and $s \in \text{Ext}(K^*)$ with $\langle x, s \rangle = 0$.

Lemma (Orlitzky, 2017).

If
$$K = \text{cone}(G_1)$$
 and if $K^* = \text{cone}(G_2)$, then

L is Lyapunov-like on K

$$\iff$$

$$\langle L(x), s \rangle = 0$$
 for all $x \in G_1$
and $s \in G_2$ with $\langle x, s \rangle = 0$.

We can check a polyhedral cone in finite time.

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Most basic results go through to the general case, but the following (surprisingly) does not.

Proposition (Rudolf et al., 2011).

If K and H are proper cones, then

$$\beta(K \times H) = \beta(K) + \beta(H).$$

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Theorem (Orlitzky, 2017).

If K is a closed convex cone in V, then

$$\beta(K) = \beta(K_{SP}) + \lim(K)\dim(K) + \operatorname{codim}(K)\dim(V).$$

where K_{SP} is a proper subcone of K in an appropriate subspace.

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The previous theorem provides a shortcut for computing the Lyapunov rank of improper cones.

Input: A cone K

Output: The Lyapunov rank of K

$$\beta \leftarrow 0$$

$$n \leftarrow \dim(V)$$

$$m \leftarrow \dim(K)$$

$$l \leftarrow \ln(K)$$

$$\begin{aligned} & \text{if } m < n \text{ then} \\ & K \leftarrow \text{RESTRICT}\left(K, \text{span}\left(K\right)\right) \\ & \beta \leftarrow \beta + (n-m) \, n \\ & \text{end if} \end{aligned}$$

$$& \text{if } l > 0 \text{ then} \\ & K \leftarrow \text{RESTRICT}\left(K, \text{span}\left(K^*\right)\right) \\ & \beta \leftarrow \beta + lm \\ & \text{end if} \end{aligned}$$

return β + card (LL (K)) \triangleright K is proper here

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And when K is polyhedral, we can run it.

```
sage: K = random_cone(); K
12-d cone in 34-d lattice N
sage: timeit('K.lyapunov_like_basis()')
5 loops, best of 3: 10.8 s per loop
sage: timeit('K.lyapunov_rank()')
5 loops, best of 3: 289 ms per loop
```

Theorem (Gowda and Tao, 2014).

If K is a proper polyhedral cone in \mathbb{R}^n , then

$$1 \le \beta(K) \le n \text{ and } \beta(K) \ne n-1.$$

Theorem (Orlitzky, 2017).

If K is a polyhedral cone in V, then

$$\beta(K) \neq \dim(V) - 1.$$

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Theorem (Gowda and Tao, 2014).

If K is a proper cone and if L is linear, then the following are equivalent:

- L is Lyapunov-like on K.
- $e^{tL} \in \text{Aut}(K)$ for all $t \in \mathbb{R}$.
- $L \in \text{Lie}(\text{Aut}(K))$.

Theorem (Orlitzky, 2017).

If K is a closed convex cone and if L is linear, then the following are equivalent:

- L is Lyapunov-like on K.
- $e^{tL} \in \text{Aut}(K)$ for all $t \in \mathbb{R}$.
- $L \in \text{Lie}(\text{Aut}(K))$.

Part 2, Section 4

Results: Lyapunov rank bound

RESULTS: LYAPUNOV RANK BOUND

Theorem (Gowda and Tao, 2014).

If K is a proper cone in an n-dimensional space, then $\beta(K) \leq n^2 - n$.

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RESULTS: LYAPUNOV RANK BOUND

Theorem (Orlitzky and Gowda, 2016).

If K is a proper cone in an n-dimensional space, then $\beta(K) \leq (n-1)^2$.

The proof involves constructing an additional n-1 elements of $\mathbf{LL}(K)^{\perp}$, beyond the n that Gowda and Tao constructed.

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RESULTS: LYAPUNOV RANK BOUND

The theorem relies on a Lemma:

Lemma (Orlitzky and Gowda, 2016).

If K is a proper cone and if its boundary is contained in a *finite* union of hyperplanes, then K is polyhedral.

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Part 2, Section 5

Results: Game theory

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A two-person zero-sum matrix game involves

- Two players,
- Two strategies x, y in the unit simplex Δ ,
- A matrix to determine the payoff.

The payoff function with respect to $A \in \mathbb{R}^{n \times n}$ is,

$$(x,y) \mapsto \langle Ax, y \rangle$$
.

The first player wants to maximize $\langle Ax, y \rangle$, and the second player wants to minimize it.

The set Δ is compact and $\langle A \cdot, \cdot \rangle$ is bilinear, so

$$\min_{y \in \Delta} \max_{x \in \Delta} \langle Ax, y \rangle$$

exists, as von Neumann showed.

Matrix games...

- 1. Can be solved by linear programs (von Neumann, 1944).
- 2. And conversely (Dantzig in the 1960s).
- 3. Conversely, really (Adler in 2013).

Thus game theory can provide insight into optimization problems.

So motivated, Gowda and Ravindran generalized matrix games to linear games.

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A linear game has two players choosing x and y from a compact base of a self-dual cone K,

$$x, y \in \Delta := \{z \in K \mid \langle z, e \rangle = 1\}.$$

Here, $e \in \text{int}(K)$ ensures that Δ is compact.

The payoff is with respect to a linear operator L:

$$(x,y) \mapsto \langle L(x), y \rangle$$
.

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Gowda and Ravindran (2015) connect linear games to cone complementarity problems.

In particular,

- If L is Lyapunov-like on K, or
- If L is **Z**-operator on K,

then the game's value has nice properties.

Orlitzky (201X) extends things to $K \neq K^*$.

The single strategy set Δ is replaced by Δ_1 and Δ_2 —one set for each player—defined in terms of $e \in \text{int } (K)$ and $e^* \in \text{int } (K^*)$.

Most results of Gowda and Ravindran generalize.

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Theorem (Orlitzky, 201X).

If,

- the value of a linear game is zero, and
- $\bar{y} \in \text{int}(K^*)$ for every optimal pair (\bar{x}, \bar{y}) ,

then the optimal pair is unique and $\bar{x} \in \text{int}(K)$.

Why generalize?

By one of our theorems, player one wants to

maximize
$$\nu$$
 subject to $x \in K$ $\langle x, e^* \rangle = 1$ $\nu \in \mathbb{R}$ $L(x) - \nu e \in K$

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Definition.

The primal cone program in standard form is,

minimize
$$\langle b, z \rangle$$

subject to $M(z) - c \in K_2$
 $z \in K_1$

where K_1 and K_2 are closed convex cones.

Theorem (Orlitzky, 201X).

Player one is trying to solve a cone program, and player two is trying to solve its dual.

(Proof by clever substitution)

We can't solve cone programs in general.

But we can solve some symmetric cone programs.

Corollary.

If K is a symmetric cone, then the associated game is solved by a symmetric cone program.

This brings us back to the setting of Gowda and Ravindran, albeit with two strategy sets Δ_1 and Δ_2 instead of just Δ .

But it lets us solve linear games numerically.

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For example, rock-paper-scissors...

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```
>>> print(G.solution())
Game value: 0.0000000
Player 1 optimal:
  [0.3333333]
  [0.3333333]
  [0.3333333]
Player 2 optimal:
  [0.3333333]
  [0.3333333]
  [0.3333333]
```

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